

## 500 series, hollow shaft encoders

### Description:

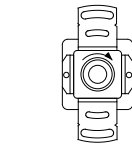
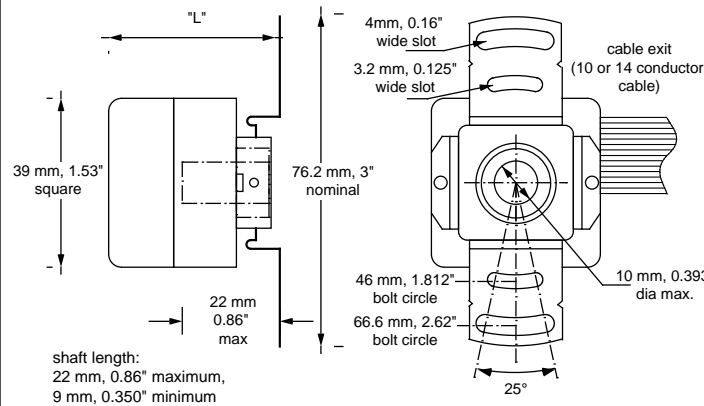
The 500 series hollow shaft encoder is a small, rugged device, with a package form factor of that of a 39 mm stepper motor. Maximum possible shaft size is 10mm. The commutating versions are specifically designed to commutate brushless DC motors.

The encoder light source is a single light emitting diode, servo controlled for constant light output over time and temperature, the sensor is a monolithic silicon array.

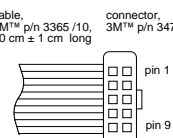
The package supports a wide variety of electronics: incremental, incremental with three bits absolute, as well as 8 and 10 bits absolute. The sine/cosine versions allow a high degree of interpolation because of the low distortion waveform for extremely accurate positioning and speed control.

### Options

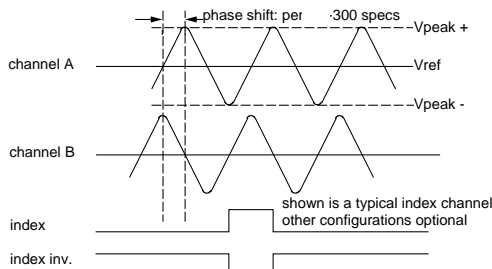
- custom linecounts, pole counts and index configurations
- custom cable configurations & other flex mounts available
- the 550, 550-08GC and 560 support a shaft extension through the back, end slotted.



all waveforms shown for cw rotation



## 500, incremental, sinusoidal



### electrical data

- power supply: ± 12 Vdc @ 60 mA max (standard)
- LED supply: AGC driven (constant light over time and temperature)
- code: incremental
- cycles per revolution: 360, 500, 600, 1000, 1024 c/r standard
- output format: A and B channel in quadrature+ Index
- output: TIL 084 op-amp flat up to 75 kHz
- frequency response: absolute accuracy of zero-crossings: ± 25 arcseconds typ.

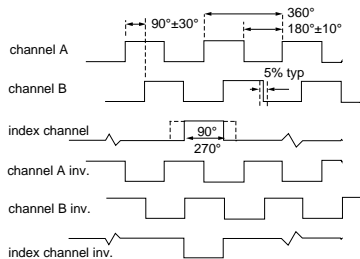
### pin assignments

- 1 ground
- 2 channel A
- 3 n/c
- 4 - 12 Vdc
- 5 n/c
- 6 channel B
- 7 n/c
- 8 + 12 Vdc
- 9 Vreference (servo ground input)
- 10 index (red stripe on cable)

**ordering information:** V<sub>cc</sub>, V<sub>ref</sub> and V<sub>peak</sub> are customer specified and depend on the controller circuitry used. Contact factory for best configuration.

**overall length:** L<sub>max</sub> = 40 mm

## 550, incremental



### electrical data:

- power supply: + 5Vdc ± 10% @ 50 mA max (no load)
- output format: incremental
- cycles/revolution: 100, 200, 256, 360, 500, 600, 1000 and 1024 std.
- frequency response: 150 kHz min. @ 85 °C
- linedriver output: 26LS31, EIA std. RS 422 and DIN 66259 compatible
- TTL output: 74LS04
- open collector output: LM 339, 6 mA max. sink

### pinout linedrivers:

- 1 + 5Vdc
- 2 + 5Vdc
- 3 channel A inv.
- 4 channel A
- 5 channel B inv.
- 6 channel B
- 7 index channel
- 8 ground
- 9 index channel inv.
- 10 ground

### pinout TTL:

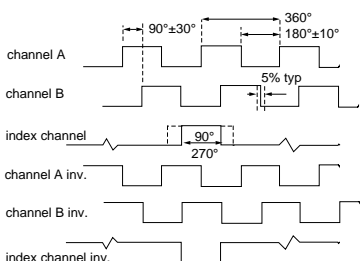
- channel A + 5 Vdc
- ground
- ground
- ground
- ground
- + 5 Vdc
- channel B
- n/c
- index channel

### ordering information:

- 550-(linecount)-(1)-(2)
- (1): linedriver=L, TTL=T, open collector=O
- (2): through-shaft with slot=X

**overall length:** L<sub>max</sub> = 40 mm

## 560, incremental linedriver 5V to 30V



### electrical data:

- power supply: V<sub>in</sub> = + 4.75 Vdc to 30 Vdc @ 50 mA max (no load)
- output format: incremental
- cycles/revolution: 100, 200, 256, 360, 500, 600, 1000 and 1024 std.
- frequency response: 150 kHz min. @ 85 °C
- output: EIA std. RS 422 and DIN 66259 (part 3) compatible
- output @ V<sub>in</sub>=4.75V: V<sub>OL</sub> ≥ 0.5 V @ 20 mA sink, V<sub>OH</sub> ≤ 2.5 V @ 20 mA source
- output @ V<sub>in</sub>=30 V: V<sub>OL</sub> ≥ 0.5 V @ 20 mA sink, V<sub>OH</sub> ≤ 27 V @ 20 mA source

### pinout complementary: single:

- 1 + V<sub>in</sub>
- 2 channel A
- 3 channel A inv.
- 4 channel B
- 5 channel B inv.
- 6 index channel
- 7 index channel inv.
- 8 ground
- 9 n/c
- 10 n/c
- channel A + V<sub>in</sub>
- ground
- ground
- ground
- + 5 Vdc
- channel B
- n/c
- index channel

### ordering information:

- 560-(linecount)-(1)-(2)
- (1): single-ended=S, complementary=C
- (2): through-shaft with slot=X

**overall length:** L<sub>max</sub> = 40 mm

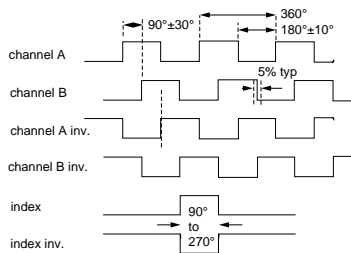
# Schmitz Engineering Liaison

124 S. Dodge Street  
P.O. Box 542  
Burlington, WI 53105

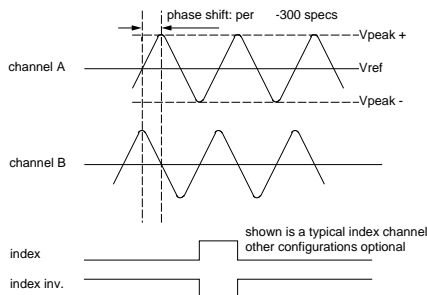
Tel: (414) 763-3036  
Fax: (414) 763-3015  
Email: encoder@encoderoptical.com  
Website: www.encoderoptical.com

## 555,565 & 505, incremental,commutating

555/ 565 A,B and Index output:



505 A,B and Index output:



### electrical data:

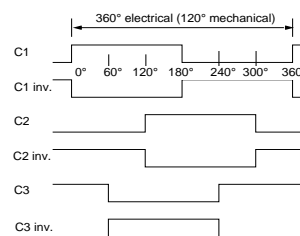
power supply 555: +5Vdc±10% @ 130 mA max (no load)  
power supply 565: +5Vdc through +30 Vdc  
power supply 505: ±12 Vdc±10% nominal @ 60 mA max (no load)  
output format: incremental + absolute  
cycles/revolution: 1000, 1024, 2048 +6 pole commutation, 1024 + 4 pole, 1024 + 8 pole  
frequency response: 150 kHz min. @ 85 °C  
linedriver output: 26LS31,EIA std. RS 422 and DIN 66259 compatible  
505 A and B out: per 500 specs

overall length:  $L_{max} = 45 \text{ mm}$

### pinout (14 pin connector)

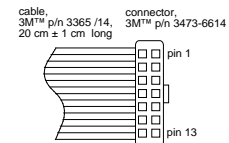
pin #	555,565	505
1	+ Vcc	+ Vcc
2	ground	ground
3	C3 inv.	C3 inv
4	C3	C3
5	C2	C2
6	C2 inv	C2 inv
7	ch. A	- Vcc
8	ch. A inv.	ch. A (sin)
9	index.	index
10	index inv.	index inv.
11	C1	C1
12	C1 inv.	C1 inv.
13	ch. B inv.	ch. B (cos)
14	ch. B	V ref

CP-505, 555 & 565 commutation channels (6 pole commutation shown):

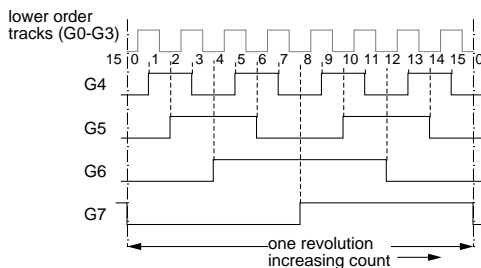


### ordering information:

square wave output:555-(1)-(2)  
square wave output:565-(1)-(2)  
sinewave output: 505-(1)-(2)  
(1) linecount / rev.  
(2) commutator information, consult factory



## 550-08GC, absolute, 8 bit Gray code



### electrical data:

power supply: +5Vdc ± 10% @ 50 mA max (no load)  
+24 Vdc ± 10% @ 70 mA max (option)  
output format: 8 bit parallel, Gray code  
frequency response: 100 kHz min. wordrate  
output: LM 339, with pullup resistor, 6 mA max. sink

overall length:  $L_{max} = 40 \text{ mm}$

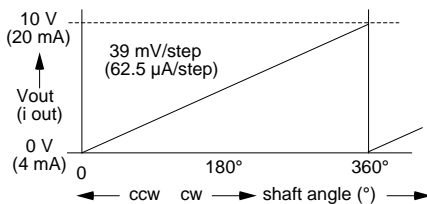
### pinout :

1	G4
2	G6
3	G0 (lsb)
4	G3
5	ground
6	G2
7	+5Vdc
8	G5
9	G7 (msb)
10	G1

### ordering information:

550-08GC-(1)-(2)-(3)  
(1): R= with pull-ups, blank if no pullups  
(2): 5 = 5 Vdc. 24 = 24 Vdc power supply  
(3): through-shaft with slot=X

## 550-8AN, absolute, analog



cw rotation of shaft for increasing  $V_{out}$  or  $I_{out}$  at direction control = "0" (low)

### electrical data:

power supply  $V_{in}$ : 12.6 Vdc to 16.6 Vdc @ 100 mA max  
voltage output  $V_{out}$ : 0 - 10 V standard,  
current output  $I_{out}$ : 4 - 20 mA (optional)  
resolution: 8 bits ( 256 steps)  
stability: ± 0.2 %  
direction control input: TTL/CMOS (5 V)

overall length:  $L_{max} = 45 \text{ mm}$

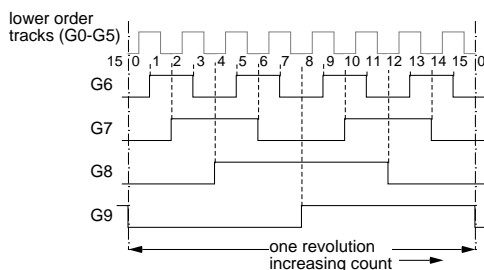
### pinout:

1	n/c
2	+ $V_{in}$
3	n/c
4	n/c
5	direction control
6	power ground
7	$I_{out}$
8	n/c
9	$V_{out}$
10	$I_{out}$ return

### ordering information:

550-08AN-(1)  
(1) : blank= $V_{out}$  only,  $I = V_{out}$  and  $I_{out}$

## 550-10GC, absolute,10 bit Gray code



### electrical data:

power supply: +5Vdc ± 10% @ 100 mA max (no load)  
output format: 10 bit parallel, Gray code,  
frequency response: 50 kHz min. wordrate  
output: standard TTL/CMOS

overall length:  $L_{max} = 45 \text{ mm}$

### pinout (14 pin connector):

1	G1
2	G8
3	G6
4	G7
5	ground
6	G5
7	+5Vdc
8	G0 (lsb)
9	G9 (msb)
10	G3
11	G4
12	G2
13	n/c
14	G9 inverted

### ordering information:

550-10GC